

# MECH 573 Mechanics of Robotic Systems

## Erratum in Page 361—February 18, 2010

First two sentences of last paragraph should read:

Additional equations free of  $\theta_1$  and  $\theta_2$  can be derived from any six of the eight equations in eq.(9.37b). Indeed, these six equations is all that is needed to solve for  $\tilde{\mathbf{x}}_{12}$  in terms of  $\theta_3$ ,  $\theta_4$  and  $\theta_5$ ; the expressions thus resulting would be then substituted into the remaining two equations of the same set, to obtain two additional equations free of  $\theta_1$  and  $\theta_2$ .