

Equations

$$(x, y) = \left(\frac{X_0}{Z_0} f, \frac{Y_0}{Z_0} f \right).$$

$$\begin{bmatrix} \sum \left(\frac{\partial I}{\partial x} \right)^2 & \sum \left(\frac{\partial I}{\partial x} \right) \left(\frac{\partial I}{\partial y} \right) \\ \sum \left(\frac{\partial I}{\partial x} \right) \left(\frac{\partial I}{\partial y} \right) & \sum \left(\frac{\partial I}{\partial y} \right)^2 \end{bmatrix} \begin{bmatrix} h_x \\ h_y \end{bmatrix} = - \begin{bmatrix} \sum (I(x, y) - J(x, y)) \frac{\partial I}{\partial x} \\ \sum (I(x, y) - J(x, y)) \frac{\partial I}{\partial y} \end{bmatrix}$$

$$\mathbf{n} \equiv \frac{1}{\sqrt{\left(\frac{\partial Z}{\partial X} \right)^2 + \left(\frac{\partial Z}{\partial Y} \right)^2 + 1}} \left(\frac{\partial Z}{\partial X}, \frac{\partial Z}{\partial Y}, -1 \right)$$

$$E(X, Y) \approx L_{src} \Omega \left\{ -l_Z + \frac{\partial Z}{\partial X} l_X + \frac{\partial Z}{\partial Y} l_Y + \frac{l_Z}{2} \left(\left(\frac{\partial Z}{\partial X} \right)^2 + \left(\frac{\partial Z}{\partial Y} \right)^2 \right) \right\}$$

$$E(X, Y) = L_{src} \int_{\mathbf{l} \in \mathcal{V}(X, Y)} \mathbf{n}(\mathbf{x}) \cdot \mathbf{l} d\Omega$$

$$I(X, Y) = \rho(X, Y) \mathbf{n}(X, Y) \cdot \mathbf{L}$$

$$(x - x_i, y - y_i) \cdot (\cos \theta, \sin \theta) = 0$$

$$\mathbf{P} = \mathbf{KR}[\mathbf{I} \mid -\mathbf{C}]$$

$$\mathbf{A}^T \mathbf{A} \mathbf{x} = \mathbf{A}^T \mathbf{b}.$$

$$\mathbf{A} = \mathbf{U} \mathbf{\Sigma} \mathbf{V}^T$$

$$\begin{bmatrix} X_{ki} - \bar{X}_k \\ Y_{ki} - \bar{Y}_k \end{bmatrix}_{2 \times N} = [\tilde{\mathbf{R}}_k]_{2 \times 3} \begin{bmatrix} X_i \\ Y_i \\ Z_i \end{bmatrix}_{3 \times N}$$

$$\mathbf{E} \equiv \mathbf{R}_2 \mathbf{R}_1^T [\mathbf{T}_1]_{\times}$$

$$\mathbf{X}_2^T \mathbf{E} \mathbf{X}_1 = 0.$$

$$d = x_{left} - x_{right}$$