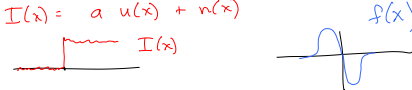


Lecture 10

- 2D edge detection
- "Corner" detection

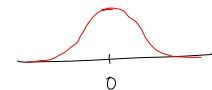
REVIEW Edge detection (Canny)

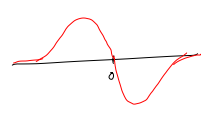
$$I(x) = a u(x) + n(x)$$


Compute $f(x) * I(x)$
and look for peak in response.

$$f(x) * I(x)$$


Choosing $f(x)$

$$g(x) = e^{-\frac{x^2}{2}}$$


$$\frac{d}{dx} g(x) = -x e^{-\frac{x^2}{2}} \equiv f(x)$$


Gaussian function ("Normal" distribution)

$$G(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}$$



$$G(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}, \quad g(x) = e^{-\frac{x^2}{2}}$$

How are the two related?

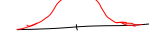
$$g_s(x) = e^{-\frac{s^2 x^2}{2}}$$

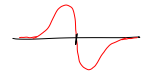
$$\frac{s}{\sqrt{2\pi}} g_s(x) = \frac{s}{\sqrt{2\pi}} e^{-\frac{s^2 x^2}{2}} = G(x) \quad \text{where } \sigma = \frac{1}{s}$$

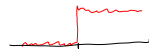
Edge detection (Canny)

$$I(x) = a u(x) + n(x)$$

Compute $\frac{d}{dx} (g(x) * I(x))$
and look for peak in response.

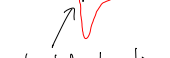
$$g(x)$$


$$\frac{d}{dx} g(x)$$


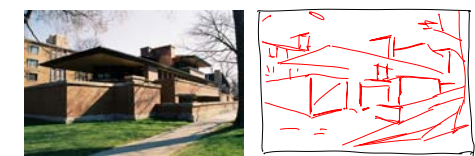
$$I(x)$$


$$I(x) * \frac{d}{dx} g(x)$$


$\frac{d}{dx} (I(x) * \frac{d}{dx} g(x))$
estimated location of edge ("zero crossing")



2D Edge Detection



Edges can occur at any orientation.

2D convolution

$$I(x,y) * f(x,y)$$

$$\equiv \sum_{x'} \sum_{y'} I(x',y') f(x-x', y-y')$$

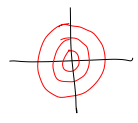
(discrete)

$$\equiv \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} I(x',y') f(x-x', y-y') dx' dy'$$

(continuous)

2D blur

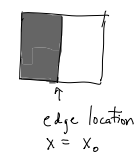
$$g(x) = e^{-\frac{x^2}{2}}$$

$$g(x,y) = e^{-\frac{x^2}{2}} e^{-\frac{y^2}{2}} = e^{-\frac{1}{2}(x^2+y^2)}$$


Vertical Edge detection

$$I(x,y) = a u(x-x_0) + n(x,y)$$

$$\text{Compute } \frac{\partial}{\partial x} (g(x,y) * I(x,y))$$



Look for pixels (x,y) where there is a peak in response in the x direction.

Horizontal Edge detection

$$I(x,y) = a u(y-y_0) + n(x,y)$$

$$\text{Compute } \frac{\partial}{\partial y} (g(x,y) * I(x,y))$$



Look for pixels (x,y) where there is a peak in response in the y direction.

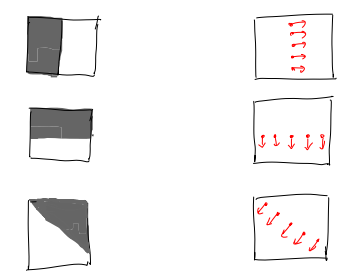
Edge detection at any orientation

$$\left(\frac{\partial}{\partial x} g(x,y) * I(x,y), \frac{\partial}{\partial y} g(x,y) * I(x,y) \right)$$

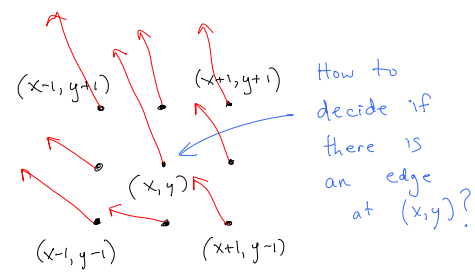
$$= \nabla (g(x,y) * I(x,y))$$

gradient operator

$$I(x,y) \quad \nabla (I(x,y) * g(x,y))$$



$$\nabla g(x,y) * I(x,y)$$



2D Edge Detection

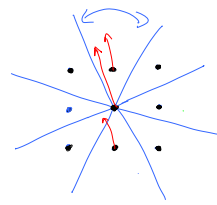
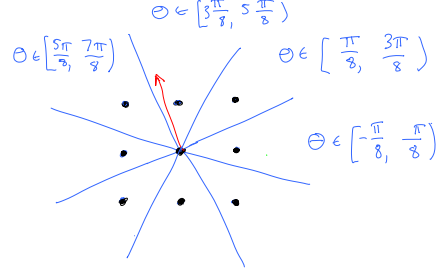
- Compute $\nabla (g(x,y) * I(x,y))$
- to decide if there is an edge at (x,y) , check for a local maxima of $|\nabla (g * I)|$ in the direction of $\nabla (g * I)(x,y)$

$$\nabla (g(x,y) * I(x,y))$$

$$= (\cos \theta, \sin \theta) \left| \nabla (g(x,y) * I(x,y)) \right|$$

To decide if there is an edge at (x,y)
 - compute $\theta(x,y)$ and look
 for maxima of $|\nabla g * I|$ in
 direction θ .

Example Approach (Trucco & Verri
 textbook)



In case $\theta \in [\frac{\pi}{8}, \frac{5\pi}{8}]$,

check that
 three conditions
 are met:

- $|\nabla g * I(x,y+1)| < |\nabla g * I(x,y)|$
- $|\nabla g * I(x,y-1)| < |\nabla g * I(x,y)|$
- $|\nabla g * I(x,y)| > \text{threshold}$

edge

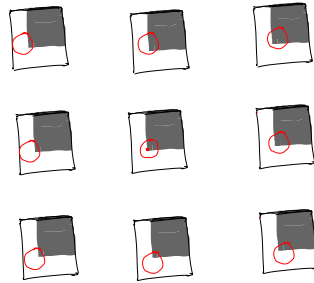


Pixels along an edge may be
 difficult to distinguish from each
 other.

Corner



Position is well defined.



Notation: write $I(x,y)$
 instead of $g(x,y) * I(x,y)$.

e.g. $\nabla I(x,y)$ instead of
 $\nabla g(x,y) * I(x,y)$

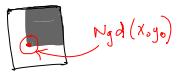
Is there a "corner" at (x_0, y_0) ?

Formulation # 1: $N_{gd}(x_0, y_0)$

How does:

$$\sum_{(x,y) \in N_{gd}(x_0, y_0)} (I(x,y) - I(x+\Delta x, y+\Delta y))^2$$

vary with $(\Delta x, \Delta y) \in \{-1, 0, 1\} \times \{-1, 0, 1\}$?



Example:

$N_{gd}(x_0, y_0)$ could be 5×5 pixels
 or a disk of diameter 5 pixels.

Formulation # 2

$$I(x+\Delta x, y+\Delta y)$$

$$\approx I(x,y) + \frac{\partial I(x,y)}{\partial x} \Delta x + \frac{\partial I(x,y)}{\partial y} \Delta y$$

$$\sum_{(x,y) \in N_{gd}(x_0, y_0)} (I(x,y) - I(x+\Delta x, y+\Delta y))^2$$

$$\approx \sum_{(x,y) \in N_{gd}(x_0, y_0)} \left(\frac{\partial I(x,y)}{\partial x} \Delta x + \frac{\partial I(x,y)}{\partial y} \Delta y \right)^2$$

$$\sum_{(x,y) \in N_{gd}(x_0, y_0)} \left(\frac{\partial I(x,y)}{\partial x} \Delta x + \frac{\partial I(x,y)}{\partial y} \Delta y \right)^2$$

$$= \sum_{(x,y) \in N_{gd}(x_0, y_0)} (\Delta x, \Delta y) \nabla I(x,y)^T \nabla I(x,y) \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

$$= (\Delta x, \Delta y) \sum_{(x,y) \in N_{gd}(x_0, y_0)} \begin{bmatrix} \left(\frac{\partial I}{\partial x}\right)^2 & \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} \\ \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} & \left(\frac{\partial I}{\partial y}\right)^2 \end{bmatrix} \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

$$\geq 0$$

Second Moment Matrix

$$M = \sum_{(x,y) \in N_{gd}(x_0, y_0)} \begin{pmatrix} \frac{\partial I}{\partial x} \\ \frac{\partial I}{\partial y} \end{pmatrix} \begin{pmatrix} \frac{\partial I}{\partial x} & \frac{\partial I}{\partial y} \end{pmatrix}$$

$$= \sum_{(x,y) \in N_{gd}(x_0, y_0)} \begin{bmatrix} \left(\frac{\partial I}{\partial x}\right)^2 & \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} \\ \frac{\partial I}{\partial x} \frac{\partial I}{\partial y} & \left(\frac{\partial I}{\partial y}\right)^2 \end{bmatrix}$$



$$M = \sum_{N_{gd}} \nabla I^T \nabla I \quad \begin{bmatrix} 23 & 0 \\ 0 & 0 \end{bmatrix} \quad \begin{bmatrix} 8 & 7 \\ 7 & 8 \end{bmatrix}$$

Is there a "corner" at (x_0, y_0) ?

Formulation # 2: $N_{gd}(x_0, y_0)$

How does quadratic form

$$(\Delta x, \Delta y) M \begin{pmatrix} \Delta x \\ \Delta y \end{pmatrix}$$

vary with $(\Delta x, \Delta y)$ on unit circle?