

Lecture 24

Overview of final exam
Review of Assignment 2

April 12, 2018

Evaluation

- Three Assignments (10% each)
- Midterm Exam (20%)
- Final Exam (50%)

You can replace your midterm exam grade with your final exam grade, i.e. final exam would be 70%.

Final Exam

50 points (28 questions, all short answer)

- 25 points on lectures 1-15 (same material as midterm)
- 25 points on eight lectures 16-23

This gives roughly equal balance to all lectures.

VISUAL IMAGE FORMATION

1. geometry ([slides](#)) ([notes](#))

origins of spatial vision, visual angle, aperture, image projection, binocular disparity

2. focus and blur ([slides](#)) ([notes](#))

sampling, thin lens equation, depth of field, accommodation, aging and abnormal vision

3. photoreceptors, color ([slides](#)) ([notes](#))

spectra: emission, reflectance, absorptance; rods and cones, metamers, color displays, color blindness

What **do** you need to know?

- everything in gray above: give definitions, do simple calculations & basic reasoning

For all subsequent slides, I will only list what you don't need to know.

VISUAL IMAGE FORMATION

1. geometry ([slides](#)) ([notes](#))

origins of spatial vision, visual angle, aperture, image projection, binocular disparity

2. focus and blur ([slides](#)) ([notes](#))

sampling, thin lens equation, depth of field, accommodation, aging and abnormal vision

3. photoreceptors, color ([slides](#)) ([notes](#))

spectra: emission, reflectance, absorptance; rods and cones, metamers, color displays, color blindness

What do you **not** need to know?

- f-number
- color displays
- temporal effects in photoreceptors

EARLY VISION

4. retina ([slides](#)) ([notes](#))

spikes, color opponency, center-surround DOGs, cross-correlation

5. orientation selectivity ([slides](#)) ([notes](#))

retinotopic maps, simple cells, Gabor models

6. disparity tuned cells ([slides](#)) ([notes](#))

complex cells in V1, monocular vs. binocular, disparity space

7. image motion 1 ([slides](#)) ([notes](#))

XYT, time dependent receptive fields, 3D Gabors and sine waves, normal velocity

8. image motion 2 ([slides](#)) ([notes](#))

motion constraint equation, intersection of constraints, velocity tuned cells (MT)

What do you **not** need to know?

- names of different types of cells in pathway
- XT separable receptive fields

3D SURFACE AND SPACE PERCEPTION

9. egomotion ([slides](#)) ([notes](#))
translation and direction of heading; rotation: VOR, smooth pursuit eye movements
10. depth from blur, binocular stereopsis ([slides](#)) ([notes](#))
blur on slanted planes, Panum's fusional area, accommodation-vergence conflict, random dot stereograms
11. shape from X: perspective, texture, shading ([slides](#)) ([notes](#))
vanishing points, depth gradient and texture cues, slant & tilt; curvature, Lambert's law
12. illumination and reflectance ([slides](#)) ([notes](#))
shape from shading (linear & cloudy day), lightness & color constancy

What do you **not** need to know?

- motion field equation formula – don't memorize (but you should know qualitatively what the component fields)
- MST model of motion estimation
- vanishing points
- formulas for slant and tilt (but you *should* know their meaning)
- formulas for shading models (but you *should* understand them)
- details of “von Kries” adaptation and “grey world” model

MEASURING AND MODELLING PERFORMANCE

13. psychophysics ([slides](#)) ([notes](#))

psychometric curves, thresholds, contrast and disparity sensitivity

14. maximum likelihood ([slides](#)) ([notes](#))

examples of likelihoods, probability review

15. cue combinations, Bayesian models ([slides](#)) ([notes](#))

priors, MAP, depth reversal ambiguity

What do you **not** need to know?

- formulas for linear cue combination (how to define cue weights?)

LINEAR SYSTEMS THEORY

16. convolution ([slides](#)) ([notes](#))

impulse response functions, complex numbers review

17. Fourier transform and filtering ([slides](#)) ([notes](#))

examples, convolution theorem, low/band/high pass filters

[after midterm starts here]

What do you **not** need to know?

- proofs that
$$\cos\left(\frac{2\pi k}{N}x\right) * \mathbb{I}(x) = a \cos\left(\frac{2\pi k}{N}x\right) + b \sin\left(\frac{2\pi k}{N}x\right)$$
$$a \cos\left(\frac{2\pi k}{N}x\right) + b \sin\left(\frac{2\pi k}{N}x\right) = \sqrt{a^2 + b^2} \cos\left(\frac{2\pi k}{N}x - \phi\right)$$
- formula for Fourier transform of Gaussian

AUDITORY IMAGE FORMATION

18. sound 1 ([slides](#)) ([notes](#))

pressure vs. intensity, dB

19. sound 2 ([slides](#)) ([notes](#))

music and speech sounds, spectrograms

What do you **not** need to know?

- null, you need to know it all

AUDITORY SYSTEM & SPATIAL HEARING

20. head and ear ([slides](#)) ([notes](#))

head and outer ear (HRIR, HRTF)

21. auditory pathway, sound localization ([slides](#)) ([notes](#))

cochlea and neural coding, duplex theory, Jeffress model, level and timing differences

22. auditory filters ([slides](#)) ([notes](#))

spectrograms revisited, critical bands and masking, spike triggered averaging and A1

23. echolocation and recognition by bats and porpoises ([slides](#)) ([notes](#))

constant frequency, frequency modulation, interference

What do you **not** need to know?

- details about human auditory bandwidths
- formula for Doppler shift
- details of constructive and destructive interference

PPT -> PDF problems on slides

$$I_{right}(t; \phi, \theta) = \underbrace{[?]_{right}(t; \phi, \theta)}_{\text{HRIR}} * I_{src}(t; \phi, \theta)$$

I will try to clean up this PDF coding stuff next week.

In the meantime, use the lecture notes to resolve ambiguities.

What else?

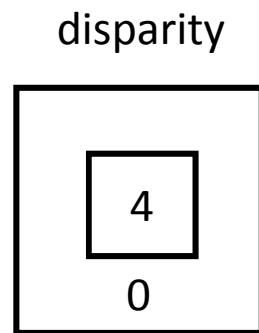
- Assignments:

If you didn't understand some questions, then review solutions. *See me if you need help.*

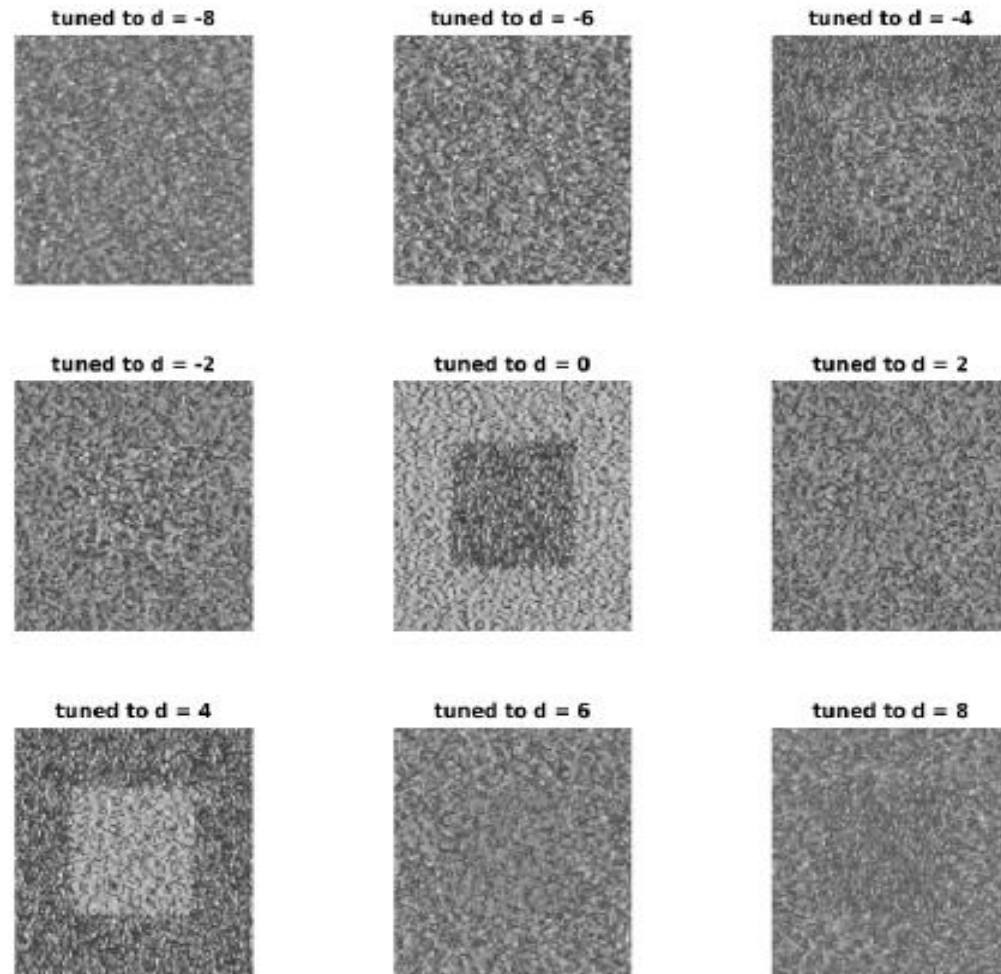
- Exercises:

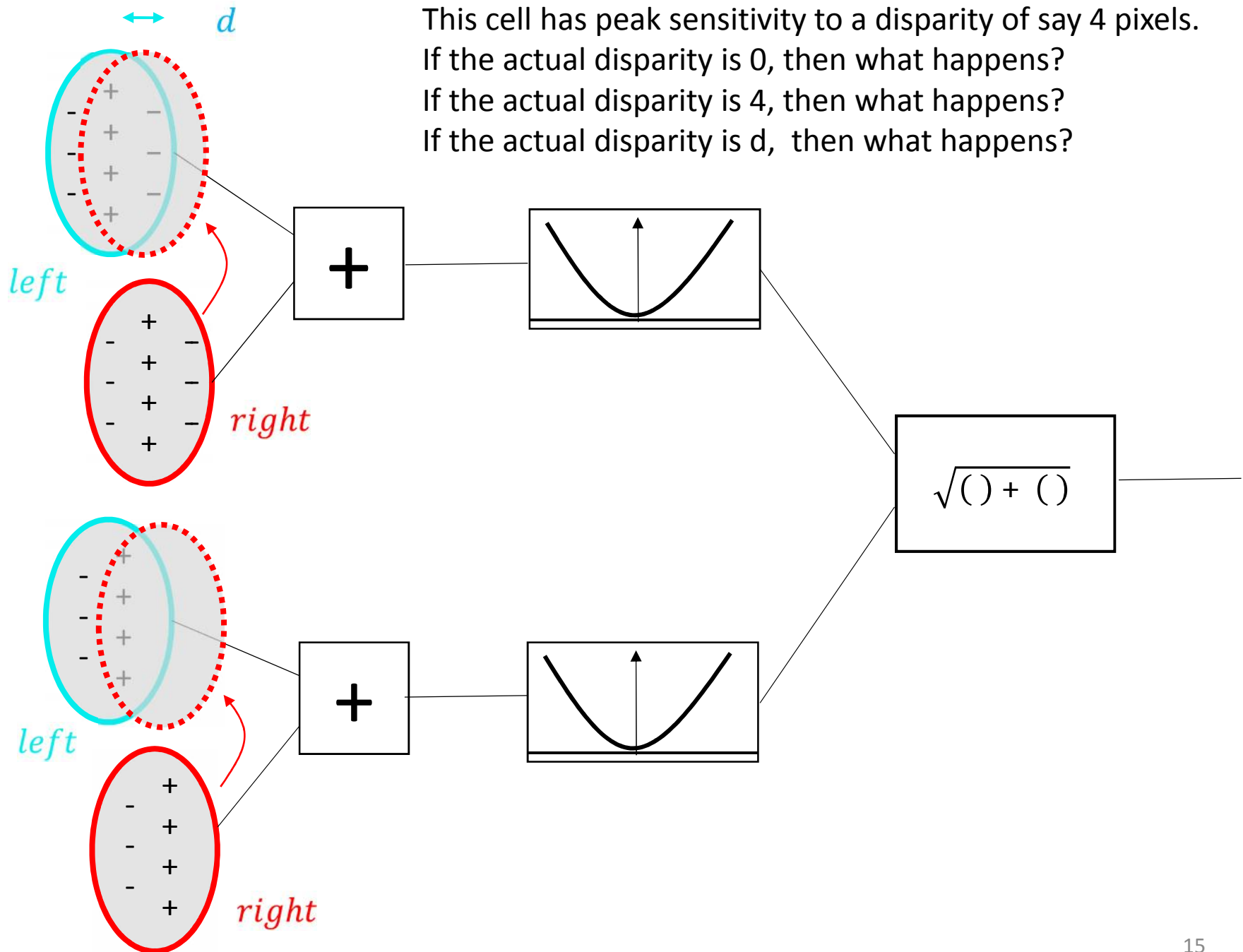
- There will be several questions on the final exam taken from Exercises
- good way of testing your understanding

Assignment 2 Question 1

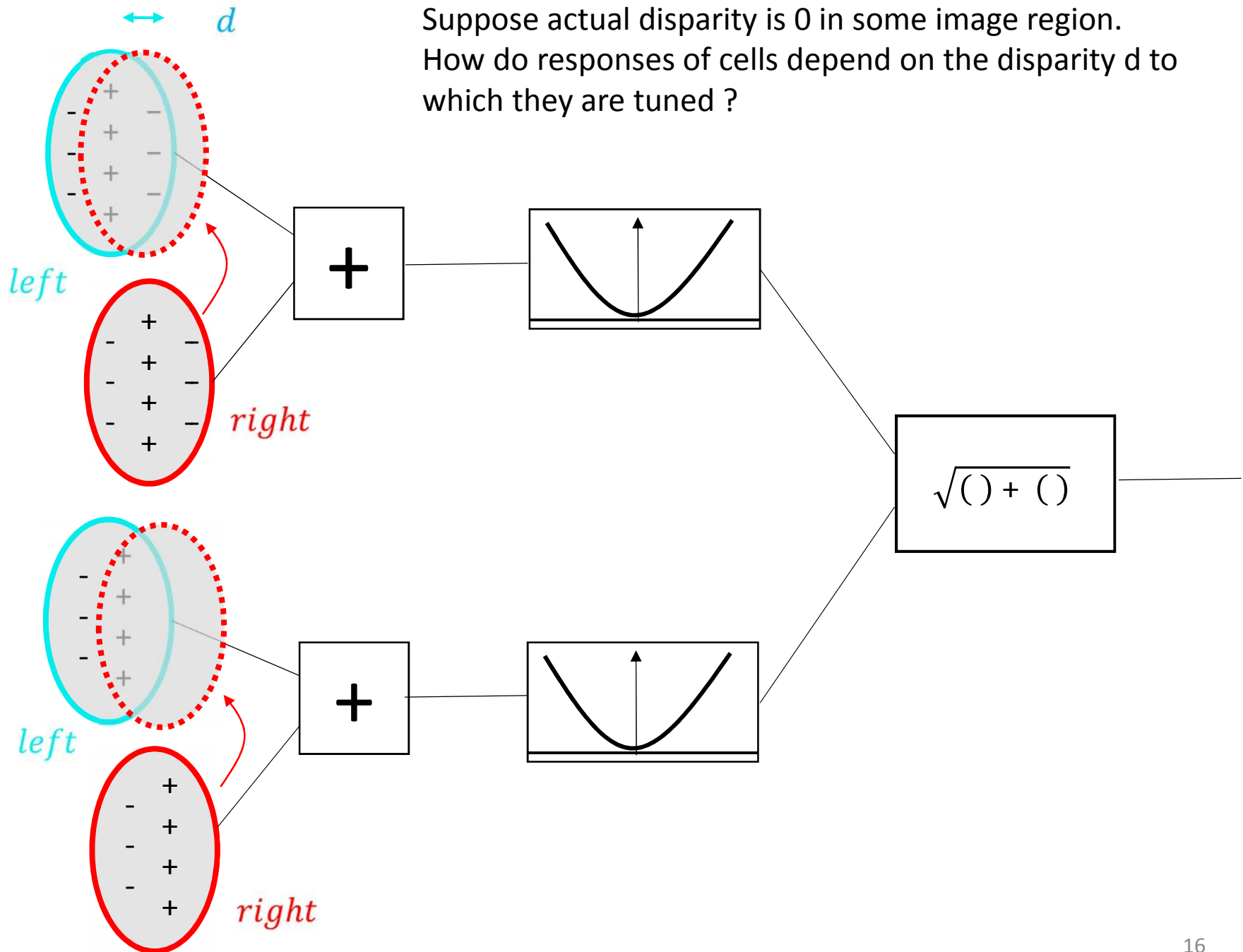


Responses of complex
Gabor cells tuned to
different disparities

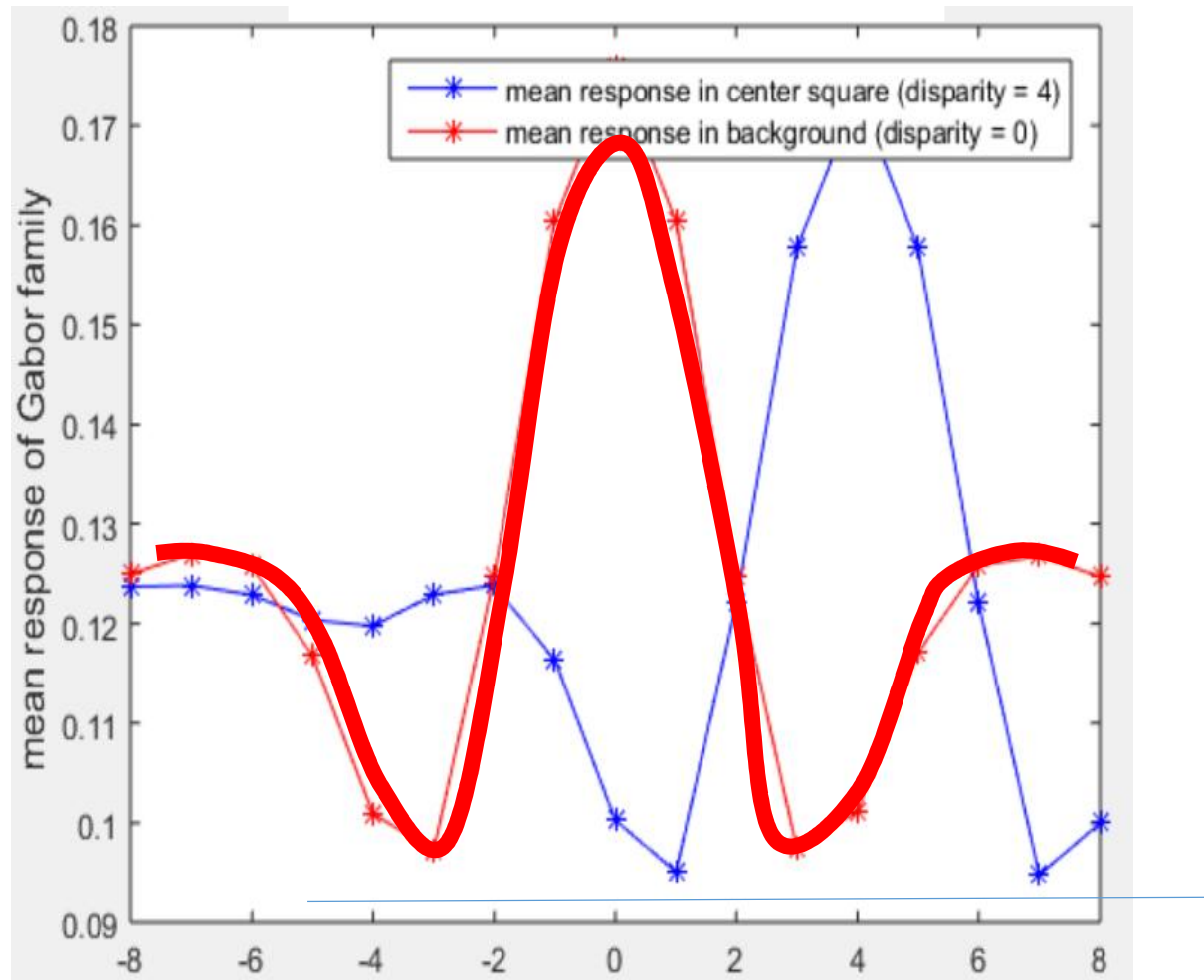




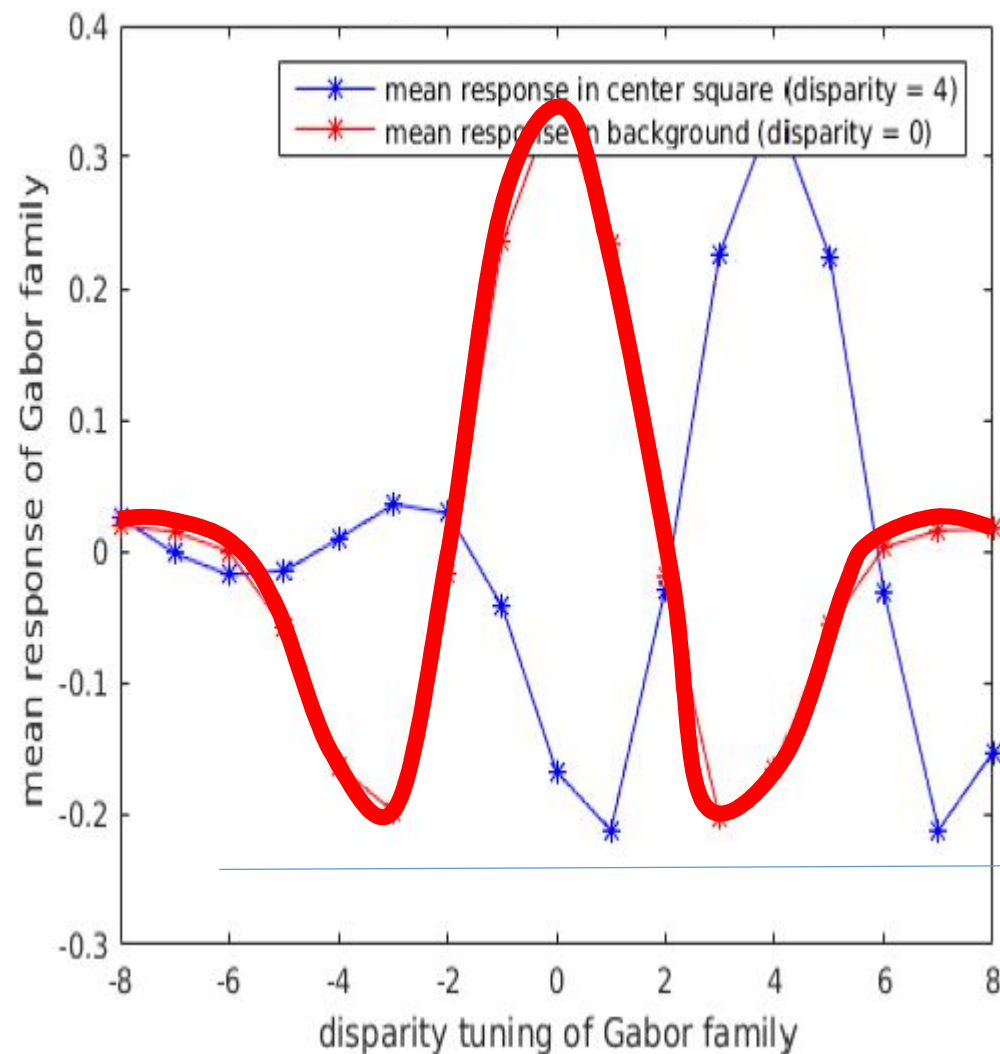
Suppose actual disparity is 0 in some image region.
How do responses of cells depend on the disparity d to which they are tuned ?



Suppose actual disparity is 0 in some image region.
How do responses of cells depend on the disparity d to which they are tuned ?



Suppose actual disparity is 0 in some image region.
How do responses of cells depend on the disparity d to which they are tuned ?

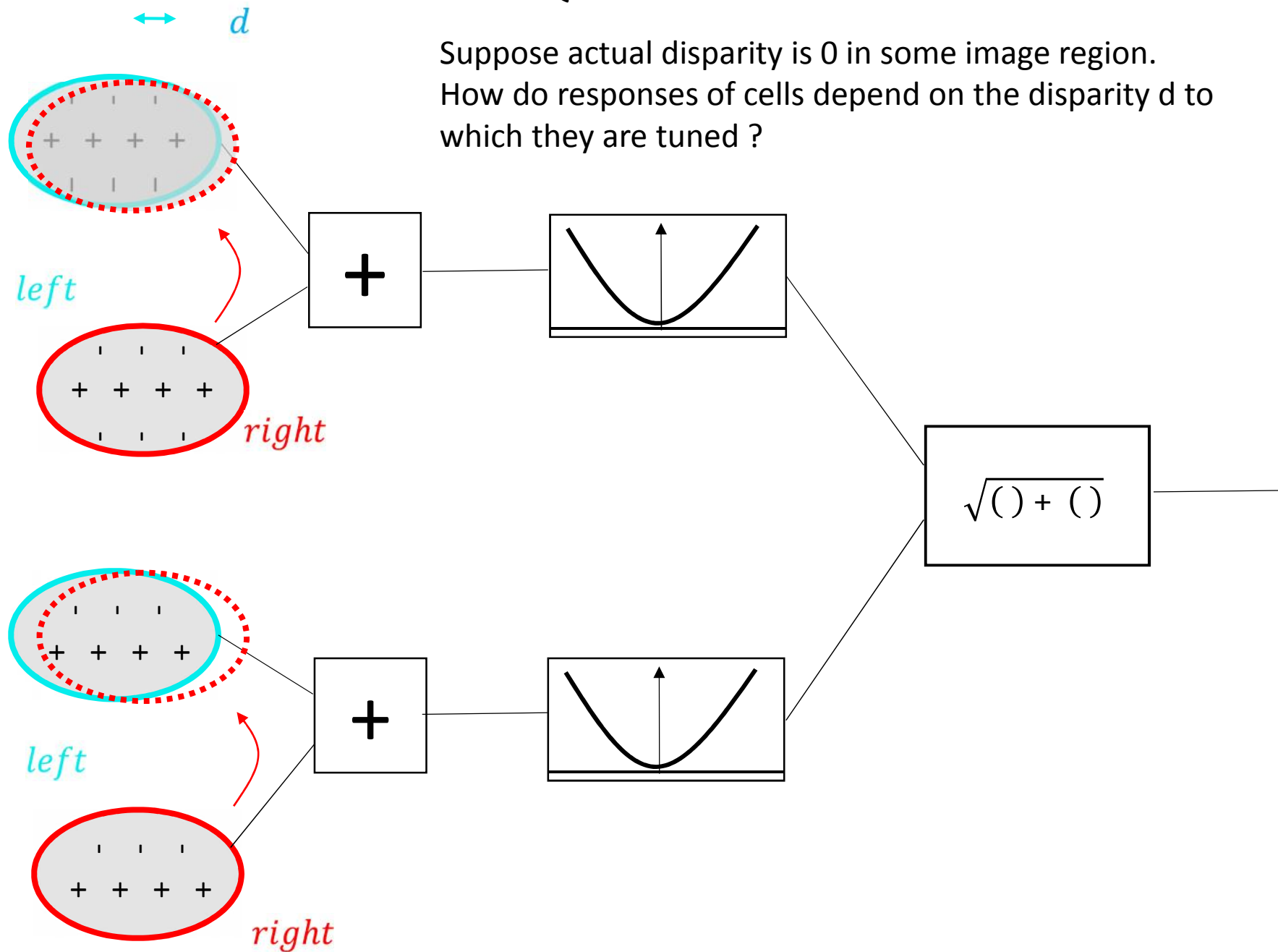


[Posted solution:]

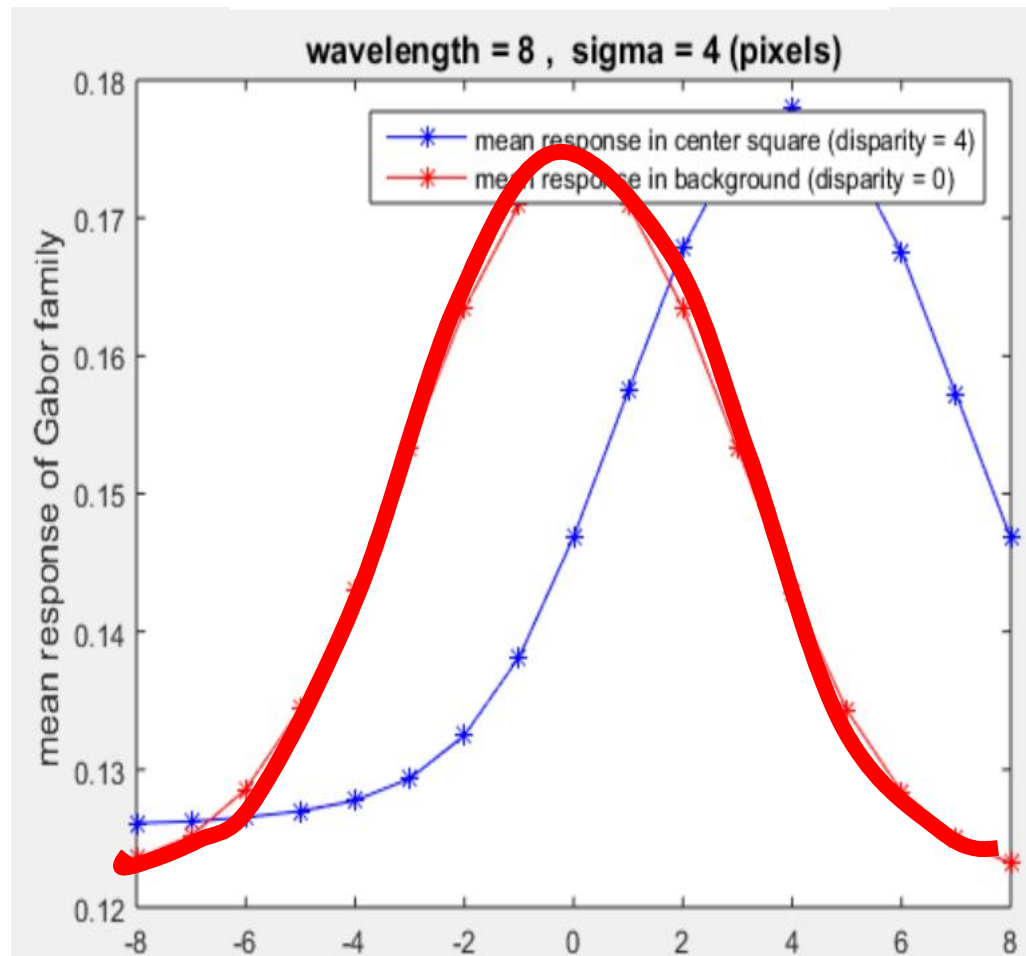
Curves shifted so
mean is 0.

Question 2

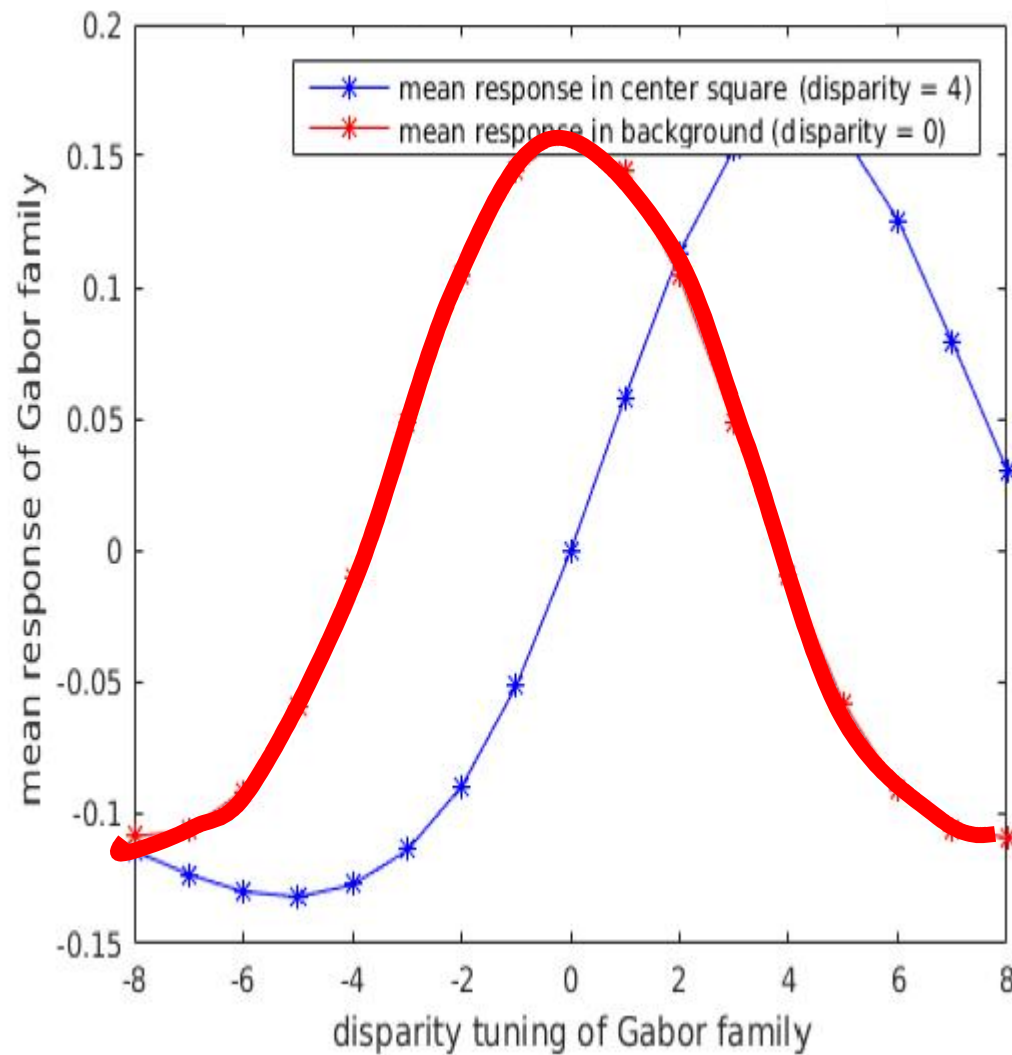
Suppose actual disparity is 0 in some image region.
How do responses of cells depend on the disparity d to which they are tuned?



Suppose actual disparity is 0 in some image region.
How do responses of cells depend on the disparity d to which they are tuned ?



Suppose actual disparity is 0 in some image region.
How do responses of cells depend on the disparity d to which they are tuned ?

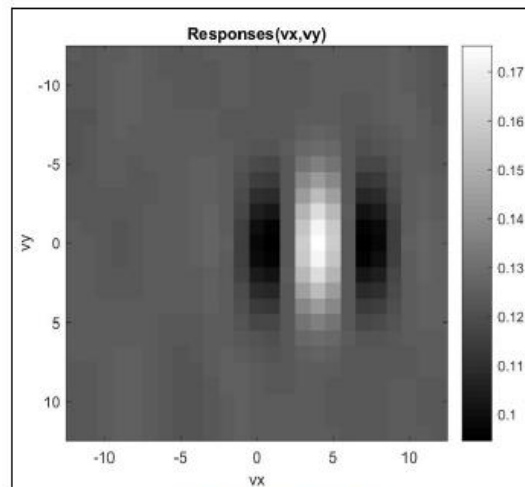


[Posted solution:]

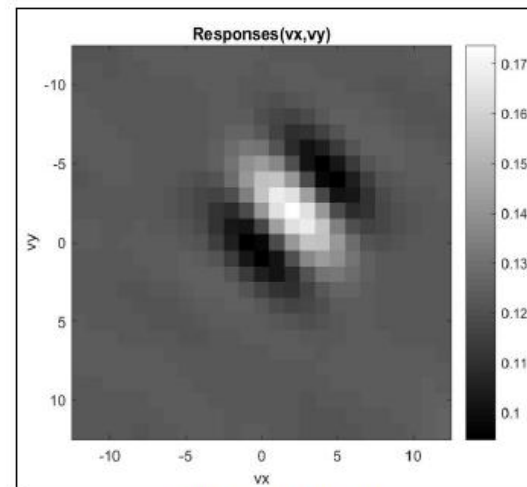
Curves shifted so
mean is 0.

Question 5

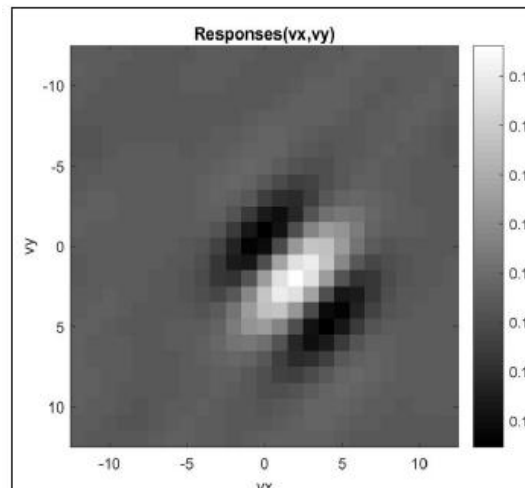
Recall the plots show responses of cells tuned to “normal velocity” (velocity in their “normal” direction).



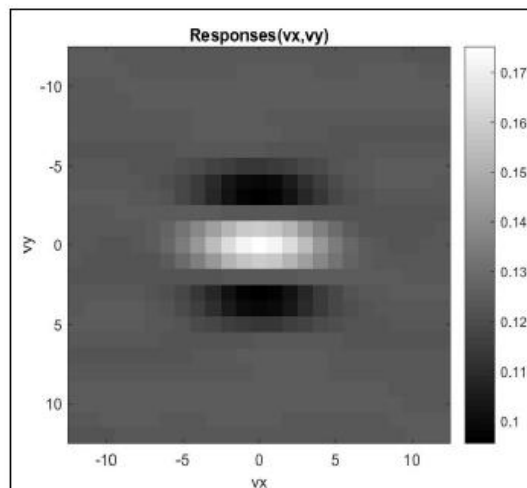
Family tuned to (4,0)



Family tuned to (2,-2)



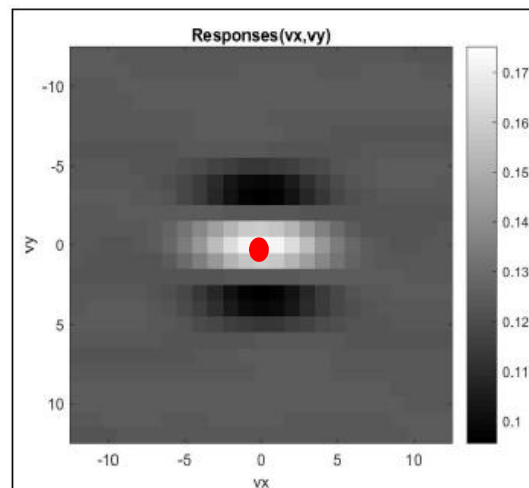
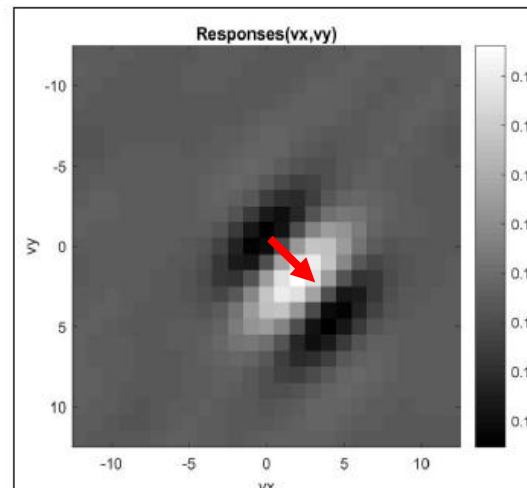
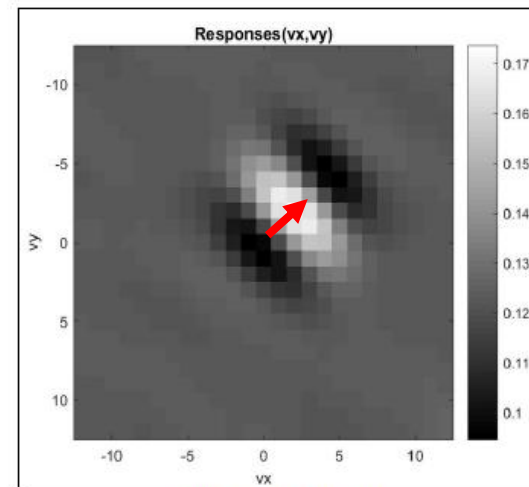
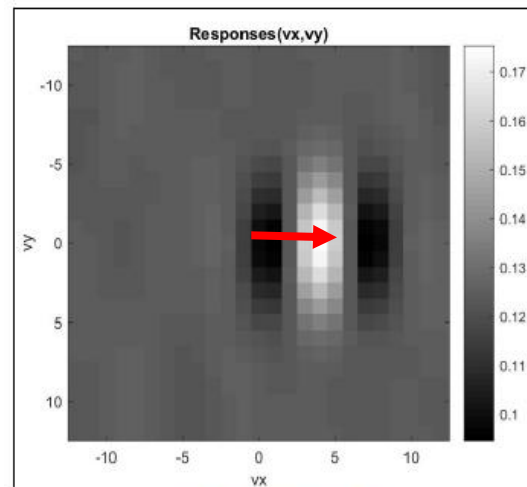
Family tuned to (2,2)



Family tuned to (0,0)

Question 5

Recall the plots show responses of cells tuned to “normal velocity” (velocity in their “normal” direction).



Normal speed = 4

Family tuned to (4,0)

Family tuned to (2,-2)

Normal speed = $\sqrt{8}$

Normal speed = $\sqrt{8}$

Family tuned to (2,2)

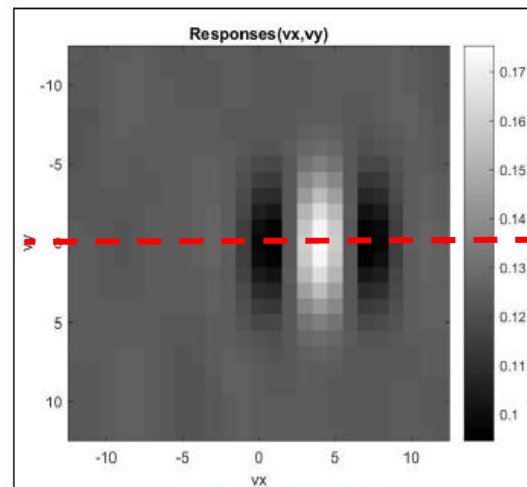
Family tuned to (0,0)

Normal speed = 0

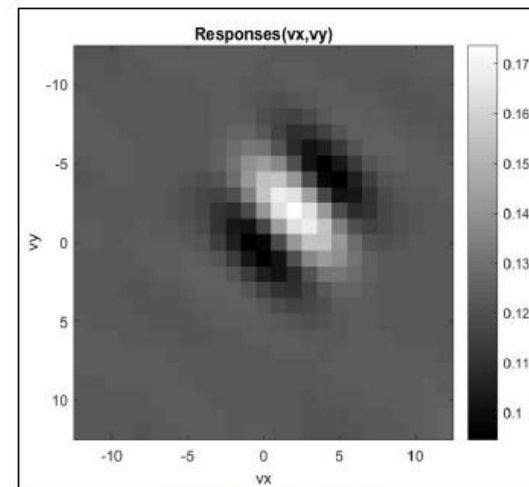
Question 5

Recall the plots show responses of cells tuned to motion in their “normal” direction to patterns moving with velocity (v_x, v_y)

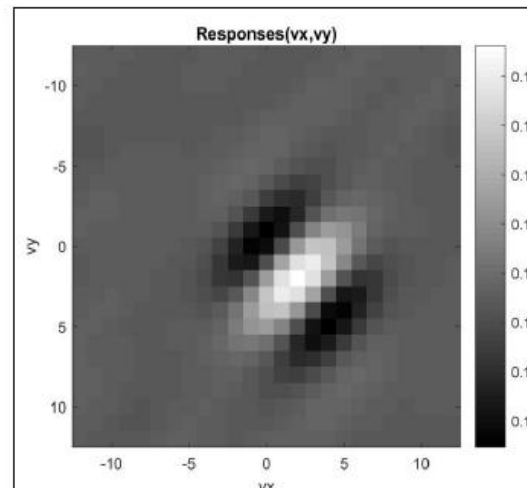
Same as Q1



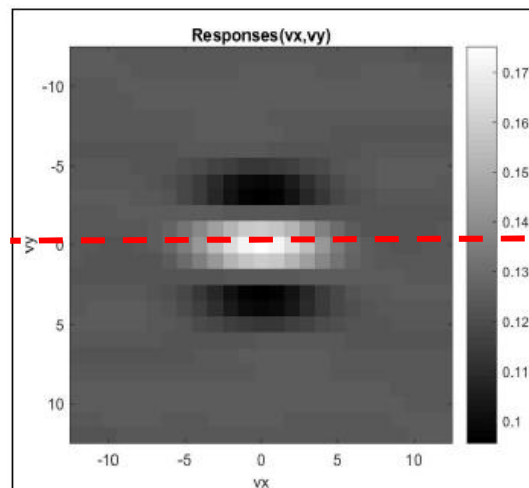
Family tuned to (4,0)



Family tuned to (2,-2)



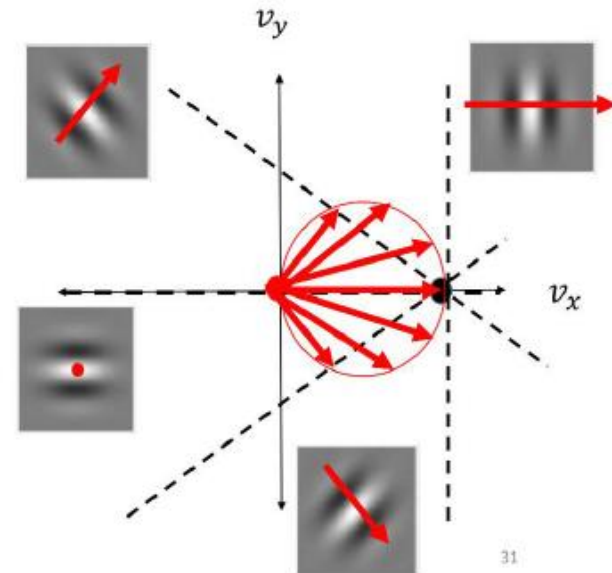
Family tuned to (2,2)



Family tuned to (0,0)

Same as Q2

Question 6



Sum of responses for chosen family of cells is biggest for velocity (4,0).

That's how I chose the cells!

To build a detector for another velocity, you would need to use a different family of cells.

True Velocity (vx,vy)	Family 1 (4,0)	Family 2 (2,-2)	Family 3 (2,2)	Family 4 (0,0)	Sum Response
(4,0)	0.1785	0.1555	0.1590	0.1464	0.6394
(-4,0)	0.1277	0.1204	0.1251	0.1464	0.5196
(0,4)	0.1171	0.1211	0.1590	0.0990	0.4962
(0,-4)	0.1172	0.1555	0.1230	0.0990	0.4947
(0,0)	0.1000	0.0982	0.0996	0.1769	0.4747

Office Hours

- Friday 10-11, 2-4
- Tuesday April 17, 10-2 + one other day that week
- Tuesday April 24, 10-2:30 + one other day that week

Please do the Course Evaluations.

Your chance to give feedback and let me and the department know what you thought.

Interested in Research or a Project?

Ugrads: COMP 396 or 400

MSc: Project or Thesis

Don't be shy. Let me know.