

# lecture 6

## Directed Graphs

- Strongly connected components
- Directed Acyclic Graphs (DAG) and Topological Orderings

## Background from COMP 250

- graph definitions  
 $G = (V, E)$ ,  $E$  represented by  
 • adjacency list or  
 • adjacency matrix
- graph traversal/search
  - depth first (stack, recursion) ← TODAY
  - breadth first (queue) ← NEXT LECTURE

See my 250 lecture notes (33, 34 + Exercises)

## Resources for this lecture

- Rough garden Algorithms I week 4

<https://class.coursera.org/algo-004/lecture/52>

<https://class.coursera.org/algo-004/lecture/53>

<https://class.coursera.org/algo-004/lecture/54>

} advanced topic (SCC fast)

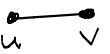
- Sedgewick Algorithm 2 week 1

<https://class.coursera.org/algs4partII-002/lecture/11>

<https://class.coursera.org/algs4partII-002/lecture/10>

} lots of nice examples

Undirected graph  $G = (V, E)$   
- edges are unordered pairs of vertices  $e = \{u, v\}$



Directed graph  $G = (V, E)$   
- edges are ordered pairs of vertices,  $e = (u, v)$

} today

i.e.  $(u, v)$  is a different edge than  $(v, u)$



Two vertices  $u, v \in V$  in a directed graph are "mutually reachable" if there is a path from  $u$  to  $v$  and a path from  $v$  to  $u$ .



### Notes:

- if  $u$  and  $v$  are mutually reachable, then there is a cycle that contains them
- every vertex is "reachable" from itself by a path of length 0.

### Recall from last lecture:

For an undirected graph, we can partition  $V$  into "connected components": sets of vertices that are connected by a path.

The corresponding definition for directed graphs is "strongly connected components".

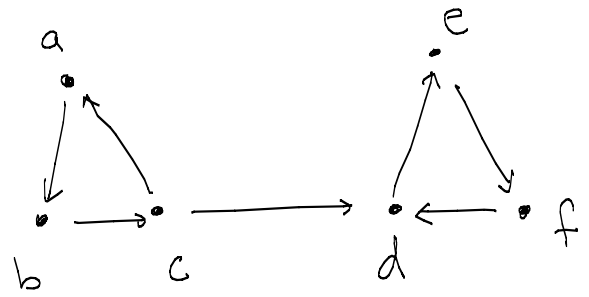
Claim: "mutually reachable" defines an equivalence relation (recall lecture 5)

Proof: Let  $\leftrightarrow$  mean mutually reachable. Then it's easy to see that:

- 1)  $v \leftrightarrow v$  (reflexive)
- 2)  $v \leftrightarrow w \Rightarrow w \leftrightarrow v$  (symmetric)
- 3)  $u \leftrightarrow v$  and  $v \leftrightarrow w \Rightarrow u \leftrightarrow w$  (transitive)

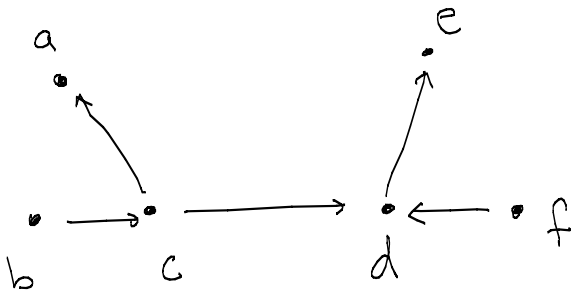
The equivalence classes (i.e. the sets in the partition) are called the "strongly connected components" (SCCs)

Q: what are the SCC's ?



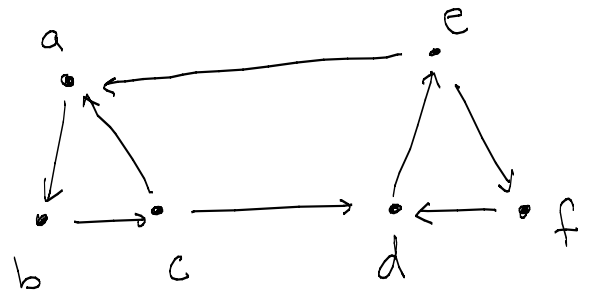
A:  $\{a, b, c\}$   $\{d, e, f\}$

Q: what are the SCC's ?



A:  $\{a\}, \{b\}, \{c\}, \{d\}, \{e\}, \{f\}$

Q: what are the SCC's ?



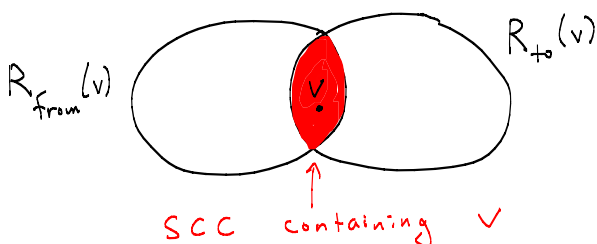
A:  $\{a, b, c, d, e, f\}$

Q: Given a graph and a vertex  $v$ , how can we find the SCC containing  $v$  ?

A: Let  $R$  mean 'reachable'.

$$R_{\text{from}}(v) = \{u : v \rightsquigarrow u\}$$

$$R_{\text{to}}(v) = \{u : u \rightsquigarrow v\}$$



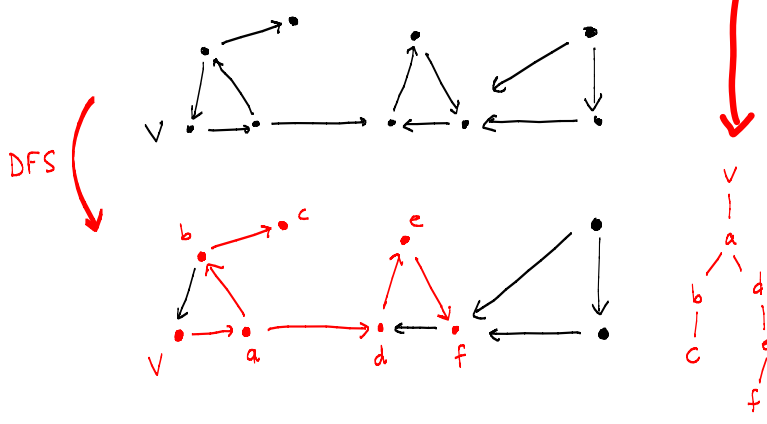
Q: How to compute  $R_{\text{from}}(v)$  ?

A: DFS( $G, v$ ) {  
 $v$ . visited = true  
 for each  $w \in v$ . adjList  
 if  $!(w$ .visited)  
 DFS( $G, w$ )  
}

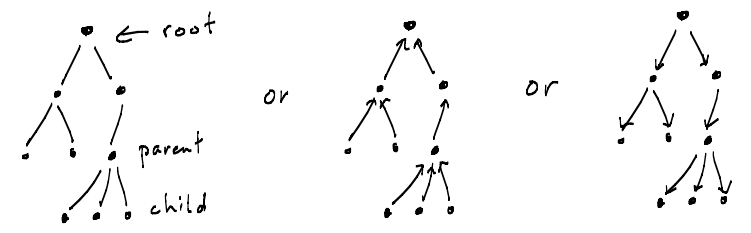
[ BFS also works, of course.]

ASIDE: Recall from COMP 250:

DFS( $G, v$ ) gives a **rooted tree**.

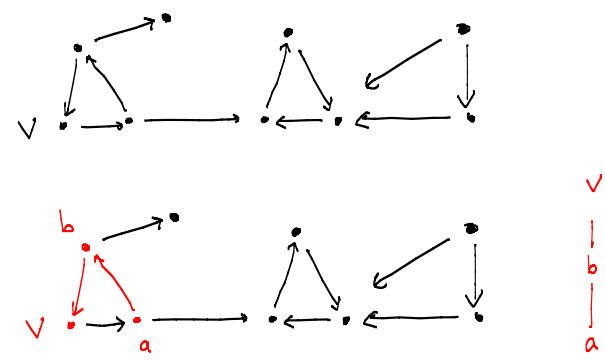


ASIDE: a "rooted tree" is a tree with one of the vertices specified as the "root". This allows us to talk about parent-child (ancestor-descendant) relationships.



Q: How to compute  $R_{to}(v)$ ?

A: Run DFS( $G, v$ ) but follow edges "backwards".



Run DFS( $G, v$ ) "backwards" means

run DFS( $G^T, v$ ) on the **reversed graph**

$$G^T \equiv (V, E^T)$$

" $G$  transpose"

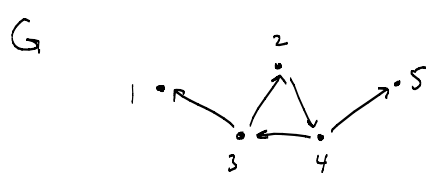
$G^T$  has same vertices as  $G$  but the edges are all reversed.

$$\text{is. } (u, v) \in E \iff (v, u) \in E^T$$

[Notation:  $G^T$  is sometimes called  $G_{rev}$ .]

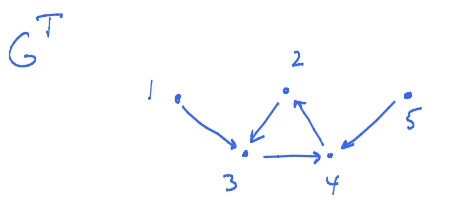
Example:

Adjacency Matrix



	1	2	3	4	5
1	0	0	0	0	0
2	0	0	1	0	0
3	1	1	0	0	0
4	0	0	1	0	0
5	0	0	0	0	0

$E$



	1	2	3	4	5
1	0	0	1	0	0
2	0	0	1	0	0
3	0	0	0	1	0
4	0	0	0	1	0
5	0	0	0	0	0

$E^T$

"transpose of  $E$ "

Say it again...

Q: Given a graph and a vertex  $v$ , how can you find the SCC containing  $v$ ?

A: DFS( $G, v$ ) gives  $R_{from}(v)$ .  
DFS( $G^T, v$ ) gives  $R_{to}(v)$ .

Compute  $R_{from}(v) \cap R_{to}(v)$



Q: Given a graph, how can you find all of the SCC's?

A:

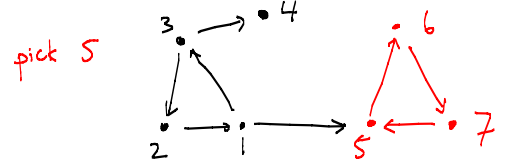
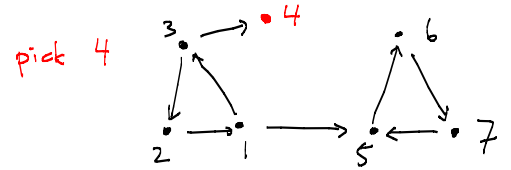
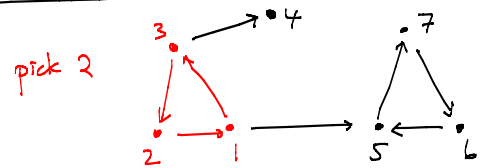
repeat {

- randomly (?) pick a vertex  $v$  for which we don't yet know its SCC
- find SCC containing  $v$

}

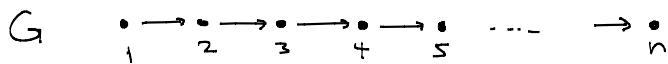
until we know SCC of all vertices

Example

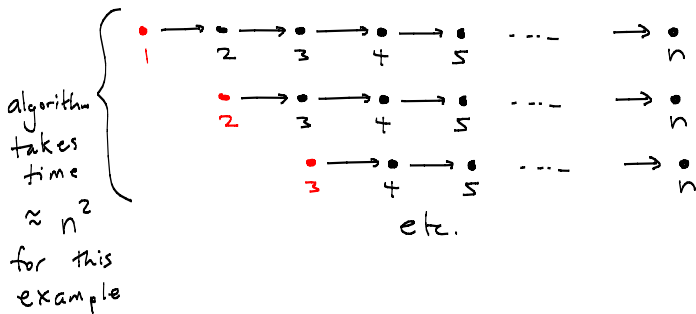


Sadly, this algorithm can be slow.

Example:  $G$  is a singly linked list



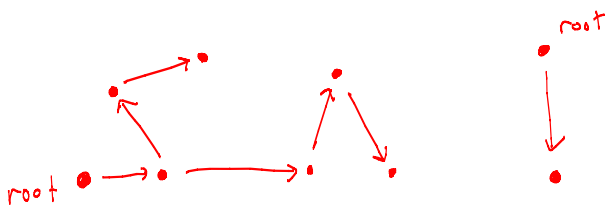
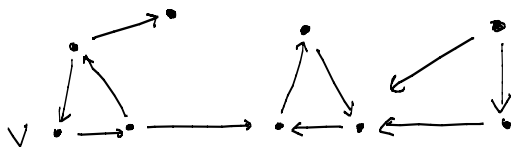
It has  $n$  strongly connected components.



There exists a simple algorithm for finding all SCC's in a graph. It is based on:

DFS( $G$ ) {  
 for all  $v$ ,  
 $v$ .reached = false  
 while there exists  $v$  such that  $!(v$ .reached)  
     DFS( $G, v$ )  
}

DFS( $G$ ) gives a forest of DFS trees.



Fast Algorithm for finding all SCCs

- 1) Run DFS( $G^T$ )
  - 2) Run DFS( $G$ )
- or swap order (doesn't matter)

NOT ON EXAM!

The clever trick [Kosaraju 1978] is how to choose  $v$  in the while loop of DFS( $G$ ), (not random!)

Sedgewick Alg. 2 → <https://class.coursera.org/algs4partII-002/lecture/11>

takes Roughgarden ~ 1 hour to go over details / example / proof {  
<https://class.coursera.org/algo-004/lecture/53>  
<https://class.coursera.org/algo-004/lecture/54>

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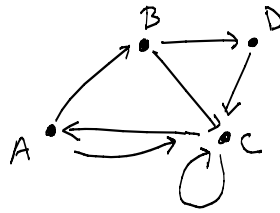
## Directed Graphs

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## Directed Acyclic Graph (DAG)

- directed graph that has no cycles  
 [a cycle is a sequence of vertices such that the first vertex is the same as the last vertex]

### Example



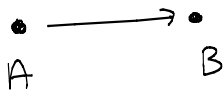
### cycles

- CC
- ACA
- ABCA
- BDCAB
- ⋮

### not cycles

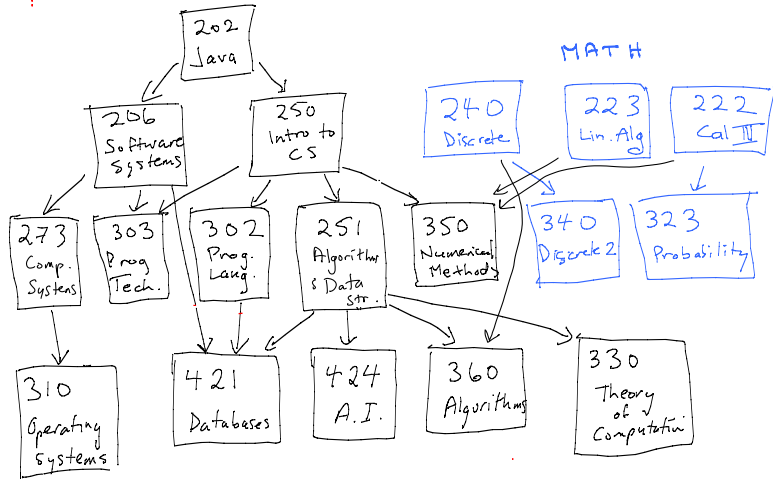
- C
- AC
- BCDB
- BDCB
- ⋮

DAGs are often used to capture dependencies between events.

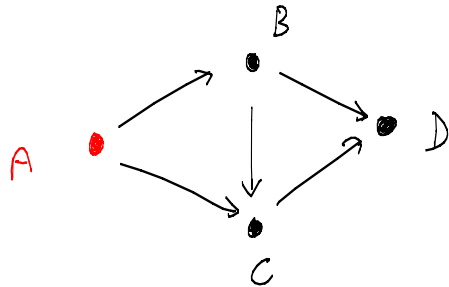


e.g. could represent that B can only occur once A has occurred.

e.g. prerequisites relation



Claim: If G is a DAG, then G must have at least one vertex with no incoming edges.

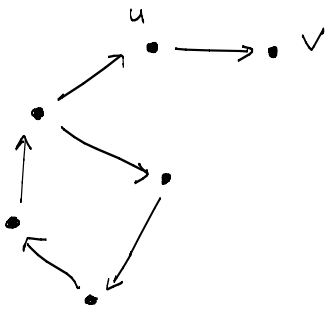


[Exercise: if G is a DAG, then G must have at least one vertex with no outgoing edges.]

Proof: (by contradiction)

Suppose every vertex of our DAG has at least one incoming edge. Pick any vertex v. v has an incoming edge (u,v), so follow it backwards to u. u has an incoming edge, so follow it backwards, etc. Eventually we must reach a vertex we have visited already (since there is a finite # vertices) But this would define a cycle.

Note the cycle might not involve  $u, v$ .



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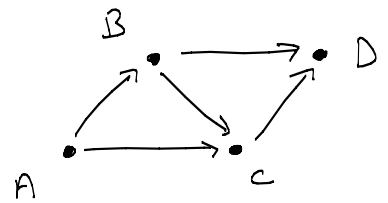
### "Topological Ordering"

Given a graph  $G=(V,E)$ , label the vertices  $v_1, v_2, \dots, v_n$  such that:

if  $(v_i, v_j) \in E$  then  $i < j$ .

This vertex ordering (when it exists!) is called a "topological ordering".

### Example



$v_1 v_2 v_3 v_4$

ABCD is a topological ordering.

ACBD is not. Why not?

Claim: If  $G=(V,E)$  is a DAG, then  $G$  has a topological ordering.

Proof: (constructive)

$G^i = G$  //  $n$  vertices,  $V^i = V$ ,  $E^i = E$   
for  $i = 1$  to  $n$  {

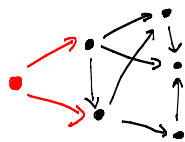
$v_i =$  a vertex in  $G^i$  with no incoming edges

$V^i = V^i \setminus \{v_i\}$

$E^i = E^i \setminus \{(v_i, w) \in E^i\}$

}

↑ "set difference"



Claim: If a directed graph  $G$  has a topological ordering, then  $G$  is a DAG.

is.  $G$  doesn't have a cycle.

Equivalent Claim: If a directed graph  $G$  has a cycle, then  $G$  does not have a topological ordering.

ASIDE: Logic: Contrapositive statement  
(MATH 240)

statement

contrapositive

"p implies q"  
"if p then q"  
 $P \Rightarrow Q$

logically equivalent

not(q) implies not(p)  
"if not(q) then not(p)"  
 $\text{not}(Q) \Rightarrow \text{not}(P)$

<http://en.wikipedia.org/wiki/Contraposition>

Equivalent Claim: If a directed graph  $G$  has a cycle, then  $G$  does not have a topological ordering.

Proof: (by contradiction)

Let the cycle be  $(v_1, \dots, v_i)$ .

If there were a topological ordering then we could write the cycle as  $(v_i \xrightarrow{\text{possibly empty}} v_j \xrightarrow{\text{possibly empty}} v_k \dots v_i)$  where  $(v_i, v_j), (v_j, v_k), \dots$  are edges in  $E$  and  $i < j < k < \dots < i$ .  
But then  $i < i$  which is obviously false.

### Announcements

- All due on Sunday night
- my office hours  
Tues & Thurs.  
11:30 - 12:30  
+ 1:00 - 2:00 pm starting next week
- Code for arraylist, linked lists, BSTs, hash table available from my COMP 250 page